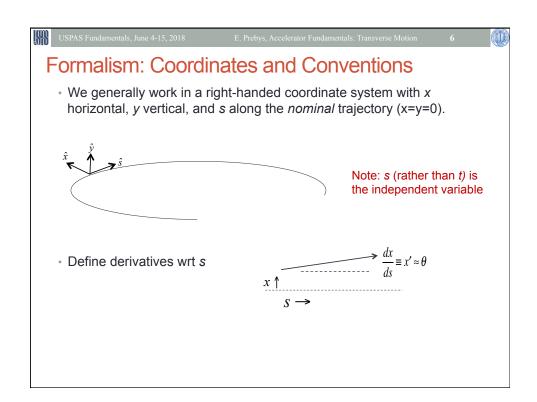


General Approach

- The dipole fields in our beam line will define an ideal trajectory.
- The position along this trajectory (s) will serve as the independent coordinate of our system.
- We will derive and explicit solution for equations of motion for *linear* focusing or defocusing effect due to deviation from this idea trajectory
 - · Linear field gradients (quadrupole term)
 - Curvilinear coordinate system (centripetal term)
- Everything else will be treated as a perturbation to this explicit solution



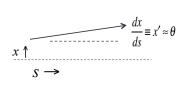


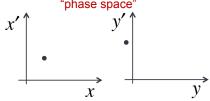
Initial Conditions and Phase Space

· Our general equations of motion will have the form

$$\frac{d^2x}{ds^2} + K_x(s)x = 0$$
$$\frac{d^2y}{ds^2} + K_y(s)y = 0$$

• These are 2nd order linear homogenous equations, so we need two initial conditions to fully determine the motion





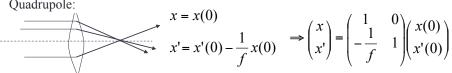
unique initial phase space point → unique trajectory



Transfer matrices

 The simplest magnetic lattice consists of quadrupoles and the spaces in between them (drifts). We can express each of these as a linear operation in phase space.







$$x(s) = x(0) + sx'(0)$$

$$x'(s) = x'(0)$$

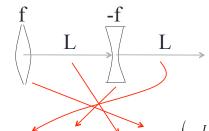
$$\Rightarrow \begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x(0) \\ x'(0) \end{pmatrix}$$

 By combining these elements, we can represent an arbitrarily complex ring or line as the product of matrices.

$$\mathbf{M} = \mathbf{M}_{N} ... \mathbf{M}_{2} \mathbf{M}_{1}$$

Example: Transfer Matrix of a FODO cell

• At the heart of every beam line or ring is the basic "FODO" cell, consisting of a focusing and a defocusing element, separated by drifts:



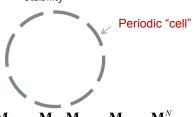
Remember: motion is usually drawn from left to right, but matrices act from right to left!

$$\Rightarrow \mathbf{M} = \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ +\frac{1}{f} & 1 \end{pmatrix} \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & L \\ -\frac{1}{f} & 1 \end{pmatrix} = \begin{pmatrix} 1 - \frac{L}{f} - \left(\frac{L}{f}\right)^2 & 2L + \frac{L^2}{f} \\ -\frac{L}{f^2} & 1 + \frac{L}{f} \end{pmatrix}$$

Can build this up to describe any beam line or ring

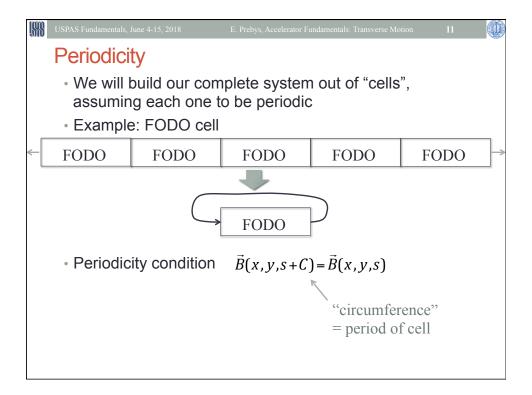
Where we're going.

- It might seem like we would start by looking at beam lines and them move on to rings, but it turns out that there is no unique treatment of a standalone beam line
 - · Depends implicitly in input beam parameters
- Therefore, we will initially solve for stable motion in a periodic system.
- The overall periodicity is usually a "ring", but that is generally divided into multiple levels of sub-periodicity, down to individual FODO cells
 - In addition to simplifying the design, we'll see that periodicity is important to stability



 $\mathbf{M}_{rine} = \mathbf{M}_{cell} \mathbf{M}_{cell} \cdots \mathbf{M}_{cell} = \mathbf{M}_{cell}^{N}$

- Our goal is to de-couple the problem into two parts
 - The "lattice": a mathematical description of the machine itself, based only on the magnetic fields, which is identical for each identical cell
 - A mathematical description of the ensemble of particles circulating in the machine ("emittance");



Quick Review of Linear Algebra

• In the absence of degeneracy, an *nxn* matrix will have *n* "eigenvectors", defined by:

$$\left(\begin{array}{ccc} M_{11} & \cdots & M_{1n} \\ \vdots & \ddots & \vdots \\ M_{n1} & \cdots & M_{nn} \end{array}\right) \left(\begin{array}{c} V_1 \\ \vdots \\ V_n \end{array}\right)_i = \lambda_i \left(\begin{array}{c} V_1 \\ \vdots \\ V_n \end{array}\right)_i$$

- · Eigenvectors form an orthogonal basis
 - That is, any vector can be represented as a unique sum of eigenvectors
- · In general, there exists a unitary transformation, such that

$$\mathbf{M'} = \mathbf{UMU}^{-1} = \begin{pmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_n \end{pmatrix} \rightarrow \mathbf{V}_i' = \mathbf{UV}_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}$$

Because both the trace and the determinant of a matrix are invariant under a unitary transformation:

$$\operatorname{Tr}(\mathbf{M}) = M_{11} + M_{22} + \dots + M_{nn} = \lambda_1 + \lambda_2 + \dots + \lambda_n$$
$$\operatorname{Det}(\mathbf{M}) = \lambda_1 \times \lambda_2 \times \dots \times \lambda_n$$



Stability Criterion

· We can represent an arbitrarily complex ring as a combination of individual matrices

$$\mathbf{M}_{ring} = \mathbf{M}_n ... \mathbf{M}_3 \mathbf{M}_2 \mathbf{M}_1$$

· We can express an arbitrary initial state as the sum of the eigenvectors of this

$$\begin{pmatrix} x \\ x' \end{pmatrix} = A\mathbf{V_1} + B\mathbf{V_2} \Rightarrow \mathbf{M} \begin{pmatrix} x \\ x' \end{pmatrix} = A\lambda_1 \mathbf{V_1} + B\lambda_2 \mathbf{V_2}$$

• After *n* turns, we have
$$\mathbf{M}^n \begin{pmatrix} x \\ x' \end{pmatrix} = A \lambda_1^n \mathbf{V_1} + B \lambda_2^n \mathbf{V_2}$$

· Because the individual matrices have unit determinants, the product must as well, so

$$Det(\mathbf{M}) = \lambda_1 \lambda_2 = 1 \rightarrow \lambda_2 = 1 / \lambda_1$$

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Stability Criterion (cont'd)

· We can therefore express the eigenvalues as

$$\lambda_1 = e^a$$
; $\lambda_2 = e^{-a}$; where *a* is in general complex

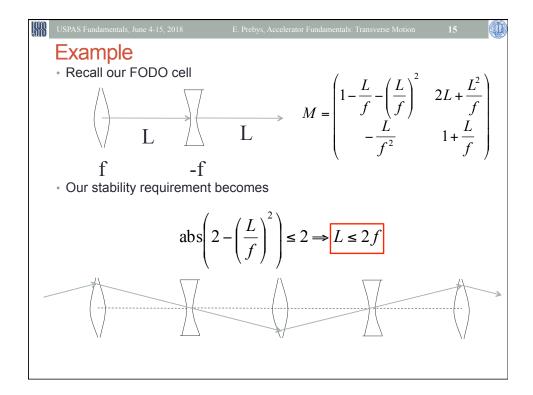
 However, if a has any real component, one of the solutions will grow exponentially, so the only stable values are

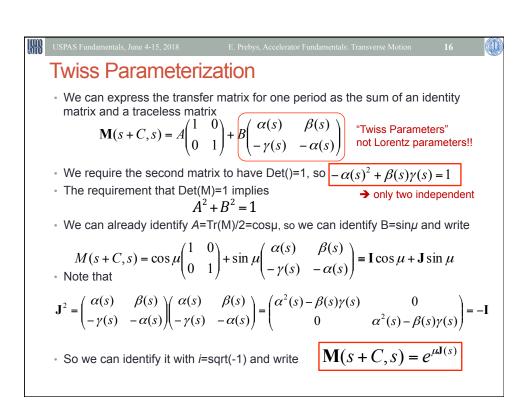
$$\lambda_1 = e^{i\mu}$$
; $\lambda_2 = e^{-i\mu}$; where μ is real

Examining the (invariant) trace of the matrix

$$Tr[\mathbf{M}] = e^{i\mu} + e^{-i\mu} = 2\cos\mu$$

So the general stability criterion is simply







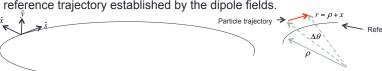
Equations of Motion

· General equation of motion

$$\vec{F} = e\vec{v} \times \vec{B} = \frac{d\vec{p}}{dt} = \frac{d}{dt} \gamma m \dot{\vec{R}} = \gamma m \ddot{\vec{R}}$$

$$\Rightarrow \ddot{\vec{R}} = \frac{e\vec{v} \times \vec{B}}{\gamma m} = \frac{e}{\gamma m} \begin{vmatrix} \hat{x} & \hat{y} & \hat{s} \\ v_x & v_y & v_s \\ B_x & B_y & 0 \end{vmatrix} = \frac{e}{\gamma m} \left(-v_s B_y \hat{x} + v_s B_x \hat{y} + \left(v_x B_y - v_y B_x \right) \hat{s} \right)$$

• For the moment, we will consider motion in the horizontal (x) plane, with a reference trajectory established by the dipole fields.



· Solving in this coordinate system, we have

$$\vec{R} = r\hat{x} + y\hat{y}$$

$$\vec{R} = \dot{r}\hat{x} + r\dot{\hat{x}} + \dot{y}\hat{y}$$

$$\vec{R} = (\ddot{r}\hat{x} + \dot{r}\dot{\hat{x}}) + (\dot{r}\dot{\theta}\hat{s} + r\ddot{\theta}\hat{s} + r\ddot{\theta}\hat{s}) + \ddot{y}\hat{y}$$

$$= (\ddot{r} - r\dot{\theta}^2)\hat{x} + (2\dot{r}\dot{\theta} + r\ddot{\theta})\hat{s} + \ddot{y}\hat{y}$$

$$= (\ddot{r} - r\dot{\theta}^2)\hat{x} + (2\dot{r}\dot{\theta} + r\ddot{\theta})\hat{s} + \ddot{y}\hat{y}$$





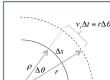
Equations of Motion (cont'd)

• Equating the x terms

$$\ddot{r} - r\dot{\theta}^2 = -\frac{ev_s B_y}{\gamma m}$$

$$= -\frac{ev_s^2 B_y}{\gamma m v_s} = -\frac{ev_s^2 B_y}{p}$$

$$= -\frac{v_s^2 B_y}{(B\rho)}$$



$$\dot{s} = \frac{ds}{dt} = \frac{\rho}{r} v_s$$

· Re-express in terms of path length s. Use

$$\frac{d}{dt} = \frac{ds}{dt}\frac{d}{ds} = v_s \frac{\rho}{r}\frac{d}{ds} \Rightarrow \frac{d^2}{dt^2} = \left(v_s \frac{\rho}{r}\right)^2 \frac{d^2}{ds^2}; \qquad \dot{\theta} = \frac{v_s}{r}$$

· Rewrite equation

$$\left(v_s \frac{\rho}{r}\right)^2 \frac{d^2 r}{ds^2} - r \left(\frac{v_s}{r}\right)^2 = -\frac{v_s^2 B}{(B\rho)^2}$$

$$r'' = -\frac{v_s^2 B_y}{\left(B\rho\right)} \frac{r^2}{\rho^2} + \frac{r}{\rho^2}$$

(use
$$r = \rho + x$$
) =

$$\int_{0}^{\infty} \left(v_{s} \frac{\rho}{r}\right)^{2} \frac{d^{2}r}{ds^{2}} - r\left(\frac{v_{s}}{r}\right)^{2} = -\frac{v_{s}^{2} B_{y}}{(B\rho)}$$

$$r'' = -\frac{v_{s}^{2} B_{y}}{(B\rho)} \frac{r^{2}}{\rho^{2}} + \frac{r}{\rho^{2}}$$

$$x'' = -\frac{B_{y}}{(B\rho)} \left(1 + \frac{x}{\rho}\right)^{2} + \frac{\rho + x}{\rho^{2}}; \quad y'' = \frac{B_{x}}{(B\rho)} \left(1 + \frac{x}{\rho}\right)^{2}$$

Equations of Motion

Expand fields linearly about the nominal trajectory

$$B_x(x, y, s) = B_x(0, 0, s) + \frac{\partial B_x(s)}{\partial x}x + \frac{\partial B_x(s)}{\partial y}y \xrightarrow{\text{no coupling no x-dipole}} \frac{\partial B_x(s)}{\partial y}y$$

$$B_{y}(x, y, s) = B_{y}(0, 0, s) + \frac{\partial B_{y}(s)}{\partial x}x + \frac{\partial B_{y}(s)}{\partial y}y \xrightarrow{\text{no coupling}} B_{0} + \frac{\partial B_{y}(s)}{\partial x}x = \frac{\left(B\rho\right)}{\rho} + \frac{\partial B_{y}(s)}{\partial x}x$$

Plug into equations of motion and keep only linear terms in x and y

$$x'' = -\frac{\left(\frac{\left(B\rho\right)}{\rho} + \frac{\partial B_{y}(s)}{\partial x}x\right)}{\left(B\rho\right)} \left(1 + \frac{x}{\rho}\right)^{2} + \frac{\rho + x}{\rho^{2}} = -\frac{1}{\rho} - \frac{1}{\left(B\rho\right)} \frac{\partial B_{y}(s)}{\partial x}x - \frac{2}{\rho^{2}}x + \frac{1}{\rho} + \frac{1}{\rho^{2}}x$$

$$\Rightarrow x'' + \left[\frac{1}{\rho^2} + \frac{1}{(B\rho)}\frac{\partial B_y(s)}{\partial x}\right]x = 0$$

$$y'' - \frac{1}{(B\rho)}\frac{\partial B_x(s)}{\partial y}y = 0$$
Looks "kinda sorta like" a harmonic oscillator

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Comment on our Equations

· We have our equations of motion in the form of two "Hill's Equations"

$$x'' + K_x(s)x = 0$$

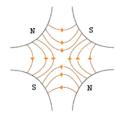
$$K > 0 \Rightarrow$$
 "focusing"

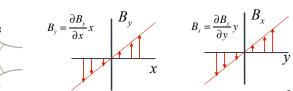
K(s) periodic!

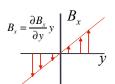
$$y'' + K_{v}(s)y = 0$$

$$K < 0 \Rightarrow$$
 "defocusing"

- This is the most general form for a conservative, periodic, system in which deviations from equilibrium small enough that the resulting forces are approximately linear
- In addition to the curvature term, this can only include the linear terms in the magnetic field (ie, the "quadrupole" term)







Note:
$$\vec{\nabla} \times \vec{B} = 0 \rightarrow \frac{\partial B_y}{\partial x} = \frac{\partial B_x}{\partial y}$$

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Comments (cont'd)

- The dipole term is *implicitly* accounted for in the definition of the reference trajectory (local curvature ρ).
- Any higher order (nonlinear) terms are dealt with as perturbations.
- Rotated quadruple ("skew") terms lead to coupling, which we won't consider yet.

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General Solution

• These are second order homogeneous differential equations, so the explicit equations of motion will be linearly related to the initial conditions by

$$\begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \begin{pmatrix} m_{11}(s) & m_{12}(s) \\ m_{21}(s) & m_{22}(s) \end{pmatrix} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

 Exactly as we would expect from our initial naïve treatment of the beam line elements.

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Piecewise Solution

- Again, these equations are in the form x'' + K(s)x = 0
- For *K* constant, these equations are quite simple. For K>0 (focusing), it's just a harmonic oscillator and we write

$$x(s) = A\cos(\sqrt{K}s + \delta) = a\cos(\sqrt{K}s) + b\sin(\sqrt{K}s)$$

$$x'(s) = -\sqrt{K}a\sin(\sqrt{K}s) + \sqrt{K}b\cos(\sqrt{K}s)$$

 In terms if initial conditions, we identify and write

$$a=x_0; b=\frac{x_0'}{\sqrt{K}}$$

$$\begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \begin{pmatrix} \cos(\sqrt{K}s) & \frac{1}{\sqrt{K}}\sin(\sqrt{K}s) \\ -\sqrt{K}\sin(\sqrt{K}s) & \cos(\sqrt{K}s) \end{pmatrix} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

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• For K<0 (defocusing), the solution becomes

$$\begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \begin{pmatrix} \cosh(\sqrt{|K|}s) & \frac{1}{\sqrt{|K|}}\sinh(\sqrt{|K|}s) \\ \sqrt{|K|}\sinh(\sqrt{|K|}s) & \cosh(\sqrt{|K|}s) \end{pmatrix} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

• For K=0 (a "drift"), the solution is simply

$$x(s) = x_0 + x_0' s$$

$$\Rightarrow \begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

We can now express the transfer matrix of an arbitrarily complex beam line with

$$\mathbf{M} = \mathbf{M}_1 \mathbf{M}_2 \mathbf{M}_3 ... \mathbf{M}_n$$

· But there's a limit to what we can do with this

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Closed Form Solution

· Our linear equations of motion are in the form of a "Hill's Equation"

$$x'' + K(s)x = 0$$
; $K(s+C) = K(s)$ Consider only periodic systems at the moment

• If K is a constant >0, then $x(s) = A\cos(\sqrt{K}s + \delta)$ so try a solution of the form

$$x(s) = Aw(s)\cos(\psi(s) + \delta)$$

assume
$$w(s + C) = w(s)$$
, BUT
 $\psi(s + C) \neq \psi(s)$

• If we plug this into the equation, we get

$$x'' + Kx = A(w'' - w\psi'^2 + Kw)\cos(\psi + \delta) - A(2w'\psi' + w\psi'')\sin(\psi + \delta) = 0$$

· Coefficients must independently vanish, so the sin term gives

$$2w'\psi' + w\psi'' = 0 \xrightarrow{\text{mutliply by } w} 2ww'\psi' + w^2\psi'' = (w^2\psi') = 0 \Rightarrow \psi' = \frac{k}{w^2}$$

· If we re-express our general solution

$$x = w(A_1 \cos \psi + A_2 \sin \psi)$$

$$x' = (A_1 w' + A_2 w \psi') \cos \psi + (A_2 w' - A_1 w \psi') \sin \psi$$

$$= \left(A_1 w' + A_2 \frac{k}{w}\right) \cos \psi + \left(A_2 w' - A_1 \frac{k}{w}\right) \sin \psi \qquad w'' - \frac{k^2}{w^3} + Kw = 0$$

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Solving for periodic motion

- Plug in initial condition ($s=0 \rightarrow \Psi=0$)
- Define phase advances over one period

$$S_c = \sin \psi(C); C_c = \cos \psi(C)$$

$$A_1 = \frac{x_0}{w}$$

$$A_2 = \frac{x_0'w - x_0w'}{k}$$

$$x(C) = x_{0}C_{c} + \left(\frac{x'_{0}w^{2} - x_{0}ww'}{k}\right)S_{c}$$

$$= \left(C_{c} - \frac{w'w}{k}S_{c}\right)x_{0} + \frac{w^{2}}{k}S_{c}x'_{0}$$

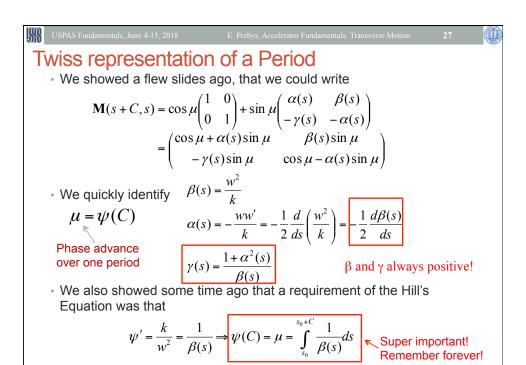
$$x'(C) = x'_{0}C_{c} + \left(\frac{x'_{0}ww'}{k} - \frac{x_{0}w'^{2}}{k} - \frac{x_{0}k}{w^{2}}\right)S_{c}$$

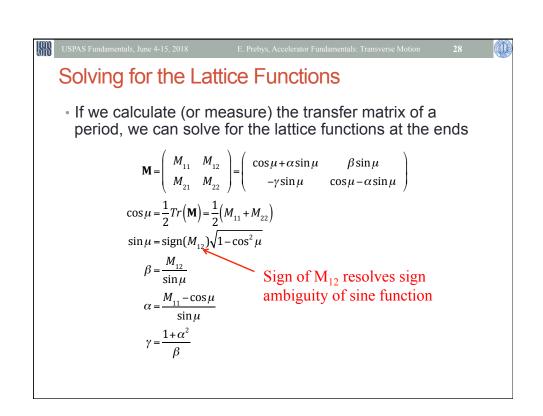
$$= \left(-\frac{k}{w^{2}} - \frac{w'^{2}}{k}\right)S_{c}x_{0} + \left(C_{c} + \frac{ww'}{k}S_{c}\right)x'$$

$$\Rightarrow \left(\begin{array}{c} x(C) \\ x'(C) \end{array}\right) = \left(\begin{array}{c} \left(C_{c} - \frac{w'w}{k}S_{c}\right) & \frac{w^{2}}{k}S_{c} \\ \left(-\frac{1 + \left(\frac{ww'}{k}\right)^{2}}{k}\right)S_{c} & \left(C_{c} + \frac{ww'}{k}S_{c}\right) \end{array}\right)$$

• But wait! We've seen this before...

This form will make sense in a minute





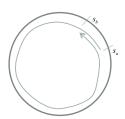
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Evolution of the Lattice Functions

- If we know the lattice functions at one point, we can use the transfer matrix to transfer them to another point by considering the following two equivalent things
 - Going around the period, starting and ending at point a, then proceeding to point b
 - Going from point a to point b, then going all the way around the period



$$\mathbf{M}(s_b + C, s_b)\mathbf{M}(s_b, s_a) = \mathbf{M}(s_b, s_a)\mathbf{M}(s_a + C, s_a)$$

$$\mathbf{M}(s_b + C, s_b) = \mathbf{M}(s_b, s_a)\mathbf{M}(s_a + C, s_a)\mathbf{M}^{-1}(s_b, s_a)$$

Recall:

$$\mathbf{J}(s) = \begin{pmatrix} \alpha(s) & \beta(s) \\ -\gamma(s) & -\alpha(s) \end{pmatrix}$$

$$\begin{aligned} \mathbf{M}(s+C,s) &= \mathbf{I}\cos\mu + \mathbf{J}(s)\sin\mu \\ \mathbf{I}\cos\mu + \mathbf{J}(s_b)\sin\mu &= \mathbf{M}(s_b,s_a) \Big(\mathbf{I}\cos\mu + \mathbf{J}(s_a)\sin\mu\Big) \mathbf{M}^{-1}(s_b,s_a) \\ &= \mathbf{I}\cos\mu + \Big(\mathbf{M}(s_b,s_a)\mathbf{J}(s_a)\mathbf{M}^{-1}(s_b,s_a)\Big)\sin\mu \\ &= \mathbf{I}\cos\mu + \mathbf{J}(s_b)\sin\mu \\ &\Rightarrow \mathbf{J}(s_b) &= \mathbf{M}(s_b,s_a)\mathbf{J}(s_a)\mathbf{M}^{-1}(s_b,s_a) \end{aligned}$$

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Evolution of the Lattice functions (cont'd)

- Using $\mathbf{M}(s_b, s_a) = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix} \Rightarrow \mathbf{M}^{-1}(s_b, s_a) \begin{pmatrix} m_{22} & -m_{12} \\ -m_{21} & m_{11} \end{pmatrix}$
- · We can now evolve the J matrix at any point as

$$\mathbf{J}(s_b) = \begin{pmatrix} \alpha(s_b) & \beta(s_b) \\ -\gamma(s_b) & -\alpha(s_b) \end{pmatrix} = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix} \begin{pmatrix} \alpha(s_a) & \beta(s_a) \\ -\gamma(s_a) & -\alpha(s_a) \end{pmatrix} \begin{pmatrix} m_{22} & -m_{12} \\ -m_{21} & m_{11} \end{pmatrix}$$

· Multiplying this mess out and gathering terms, we get

$$\begin{pmatrix} \alpha(s_b) \\ \beta(s_b) \\ \gamma(s_b) \end{pmatrix} = \begin{pmatrix} (m_{11}m_{22} + m_{12}m_{21}) & (-m_{11}m_{21}) & (-m_{12}m_{22}) \\ (-2m_{11}m_{12}) & (m_{11}^2) & (m_{12}^2) \\ (-2m_{21}m_{22}) & (m_{21}^2) & (m_{22}^2) \end{pmatrix} \begin{pmatrix} \alpha(s_a) \\ \beta(s_a) \\ \gamma(s_a) \end{pmatrix}$$



· Drift of length L:

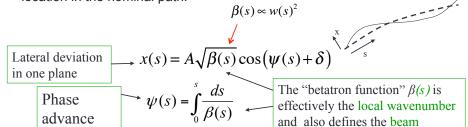
$$\mathbf{M} = \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} \alpha(s) \\ \beta(s) \\ \gamma(s) \end{pmatrix} = \begin{pmatrix} 1 & 0 & -s \\ -2s & 1 & s^2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \alpha(0) \\ \beta(0) \\ \gamma(0) \end{pmatrix} \Rightarrow \begin{pmatrix} \alpha(s) = \alpha_0 - \gamma_0 s \\ \beta(s) = \beta_0 - 2\alpha_0 s + \gamma_0 s^2 \\ \gamma(s) = \gamma_0$$

· Thin focusing (defocusing) lens:

$$\mathbf{M} = \begin{pmatrix} 1 & 0 \\ \mp \frac{1}{f} & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} \alpha' \\ \beta' \\ \gamma' \end{pmatrix} = \begin{pmatrix} 1 & \pm \frac{1}{f} & 0 \\ 0 & 1 & 0 \\ \pm \frac{2}{f} & \frac{1}{f^2} & 1 \end{pmatrix} \begin{pmatrix} \alpha_0 \\ \beta_0 \\ \gamma_0 \end{pmatrix} \Rightarrow \beta' = \beta_0 \\ \gamma' = \gamma_0 \pm \frac{2}{f} \alpha_0 + \frac{1}{f^2} \beta_0$$

Betatron motion

- Generally, we find that we can describe particle motion in terms of initial conditions and a "beta function" $\beta(s)$, which is only a function of location in the nominal path.



envelope.

Closely spaced strong quads -> small β -> small aperture, lots of wiggles

Sparsely spaced weak quads -> large β -> large aperture, few wiggles

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Behavior Over Multiple Turns

- The general expressions for motion are $x = A\sqrt{\beta}\cos\phi; \phi = \psi(s) + \delta$
- We form the combination

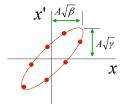
$$x' = -\frac{A}{\sqrt{\beta}} (\alpha \cos \phi + \sin \phi)$$

$$\gamma x^2 + 2\alpha x x' + \beta x'^2$$

$$=A^{2}\left(\gamma \beta \cos^{2}\phi-2\alpha^{2} \cos^{2}\phi-2\alpha \sin\phi \cos\phi+\alpha^{2} \cos^{2}\phi+\sin^{2}\phi+2\alpha \sin\phi \cos\phi\right)$$

$$=A^{2}((\gamma \beta - \alpha^{2})\cos^{2}\phi + \sin^{2}\phi)$$

- $= A^2 = constant$
- · This is the equation of an ellipse.



Area = πA^2

Particle will return to a *different* point on the *same* ellipse each time around the ring.

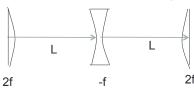
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Symmetric Treatment of FODO Cell

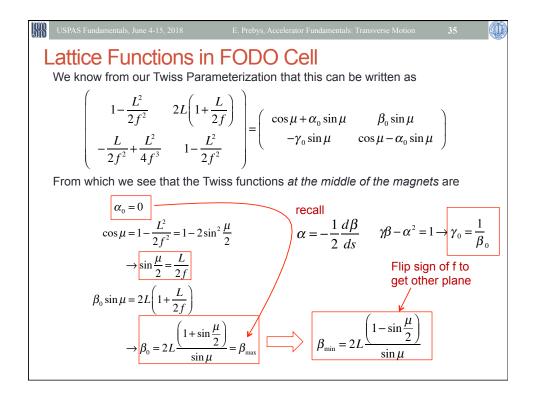
• If we evaluate the cell at the center of the focusing quad, it looks like

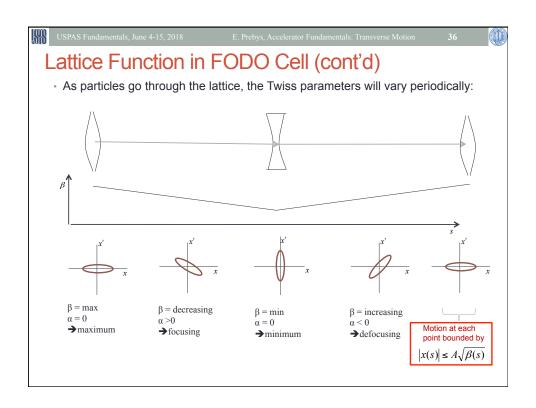


Leading to the transfer Matrix

$$M = \begin{pmatrix} 1 & 0 \\ -\frac{1}{2f} & 1 \end{pmatrix} \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \frac{1}{f} & 1 \end{pmatrix} \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & L \\ -\frac{1}{2f} & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 - \frac{L^2}{2f^2} & 2L\left(1 + \frac{L}{2f}\right) \\ -\frac{L}{2f^2} + \frac{L^2}{4f^3} & 1 - \frac{L^2}{2f^2} \end{pmatrix}$$
Note: some textbooks have L =total length







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Interlude: Some Formalism

- Let's look at the Hill's equation again... x'' + K(s)x = 0
- We can write the general solution as a linear combination of a "sine-like" and "cosine-like" term x(s) = aC(s) + bS(s) where

$$C(0) = 1; S(0) = 0$$

$$C'(0) = 0; S'(0) = 1$$

· When we plug this into the original equation, we see that

$$a(C''(s) + K(s)C(s)) + b(S''(s) + K(s)S(s)) = 0$$

 Since a and b are arbitrary, each function must independently satisfy the equation. We further see that when we look at our initial conditions

$$x(0) = aC(0) + bS(0) = a \Rightarrow a = x_0$$

$$x'(0) = aC'(0) + bS'(0) = b \Rightarrow b = x'_0$$

· So our transfer matrix becomes

$$\begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \mathbf{M} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix} \Rightarrow \begin{pmatrix} x(s) \\ x'(s) \end{pmatrix} = \begin{pmatrix} C(s) & S(s) \\ C'(s) & S'(s) \end{pmatrix} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$



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Closing the Loop

- We've got a general equation of motion in terms of initial conditions and a single "betatron function" $\beta(s)$

$$x(s) = A\sqrt{\beta(s)}\cos(\psi(s) + \delta), \quad \psi(s) = \int_0^s \frac{ds}{\beta(s)}$$

Important note!

- β (s) (and therefore α (s) and γ (s)) are defined to have the periodicity of the machine!
- In general $\Psi(s)$ (and therefore x(s)) DO NOT!
 - Indeed, we'll see it's very bad if they do

Define "tune" as the number of pseudo-oscillations around the ring

$$v = \frac{1}{2\pi} \oint \frac{ds}{\beta(s)} = \frac{1}{2\pi} N_{cell} \mu_{cell}$$

 So far, we have used the lattice functions at a point s to propagate the particle to the same point in the next period of the machine. We now generalize this to transport the beam from one point to another, knowing only initial conditions and the lattice functions at both points

$$x(s) = A\sqrt{\beta(s)}\cos(\psi(s) + \delta)$$

$$x'(s) = A \frac{1}{2} \frac{1}{\sqrt{\beta(s)}} \frac{d\beta(s)}{ds} \cos(\psi(s) + \delta) - A\sqrt{\beta(s)} \frac{d\psi(s)}{ds} \sin(\psi(s) + \delta)$$

$$= -A \frac{1}{\sqrt{\beta(s)}} \Big(\alpha(s) \cos \Big(\psi(s) + \delta \Big) + \sin \Big(\psi(s) + \delta \Big) \Big)$$







· We use this to define the trigonometric terms at the initial point as

$$C_0 = \cos(\psi(s_0) + \delta) = x_0 \frac{1}{A\sqrt{\beta_0}}$$

$$S_0 = \sin(\psi(s_0) + \delta) = -x_0' \frac{\sqrt{\beta_0}}{A} - x_0 \frac{\alpha_0}{A\sqrt{\beta_0}}$$

 We can then use the sum angle formulas to define the trigonometric terms at anv point Ψ(s₁) as

$$\cos(\psi(s_1) + \delta) = C_1 = \cos(\psi(s_0) + \delta + \Delta\psi) = C_0 \cos \Delta\psi - S_0 \sin \Delta\psi$$

$$= x_0 \left(\frac{1}{A\sqrt{\beta_0}} \cos \Delta \psi + \frac{\alpha_0}{A\sqrt{\beta_0}} \sin \Delta \psi \right) + x_0' \frac{\sqrt{\beta_0}}{A} \sin \Delta \psi$$

$$\sin(\psi(s_1) + \delta) = S_1 = \sin(\psi(s_0) + \delta + \Delta\psi) = S_0 \cos \Delta\psi + C_0 \sin \Delta\psi$$

$$=x_0 \left(\frac{1}{A\sqrt{\beta_0}}\sin\Delta\psi - \frac{\alpha_0}{A\sqrt{\beta_0}}\cos\Delta\psi\right) - x_0'\frac{\sqrt{\beta_0}}{A}\sin\Delta\psi$$





General Transfer Matrix

• We plug the previous angular identities for C₁ and S₁ into the general transport equations

$$x_1 = A\sqrt{\beta_1}\cos(\psi_1 + \delta) = A\sqrt{\beta_1}C_1$$

$$x_1' = -A \frac{1}{\sqrt{\beta_1}} (\alpha_1 C_1 + S_1)$$

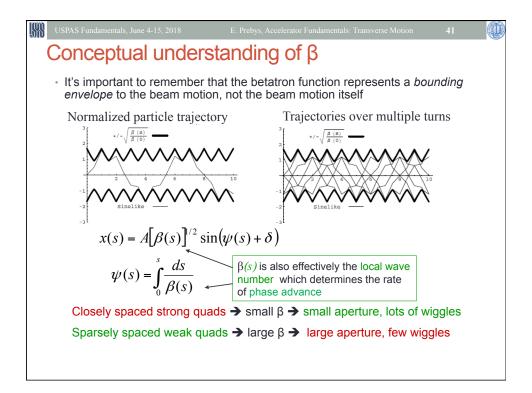
And (after a little tedious algebra) we find

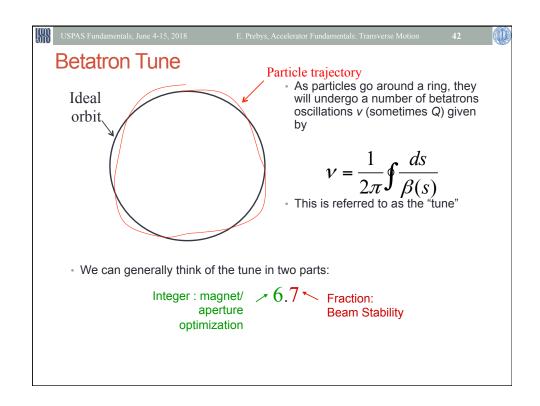
$$\begin{pmatrix} x_1 \\ x'_1 \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{\beta_1}{\beta_0}} \left(\cos \Delta \psi + \alpha_0 \sin \Delta \psi\right) & \sqrt{\beta_0 \beta_1} \sin \Delta \psi \\ \frac{1}{\sqrt{\beta_0 \beta_1}} \left(\left(\alpha_0 - \alpha_1\right) \cos \Delta \psi - \left(1 + \alpha_0 \alpha_1\right) \sin \Delta \psi\right) & \sqrt{\frac{\beta_0}{\beta_1}} \left(\cos \Delta \psi - \alpha_1 \sin \Delta \psi\right) \end{pmatrix} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

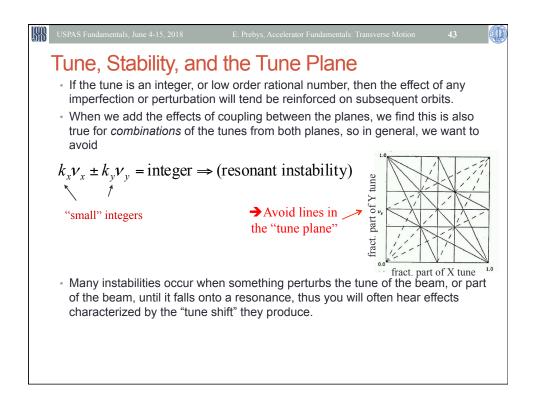
This is a mess, but we'll often

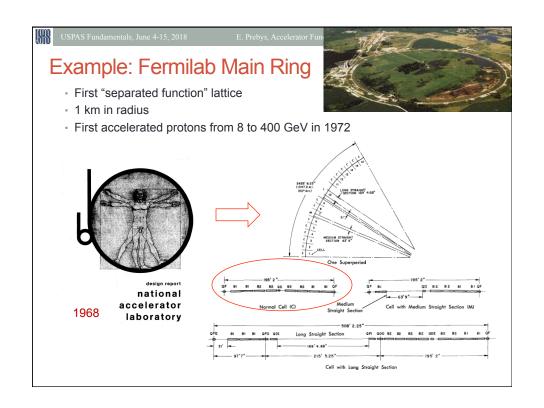
$$\alpha = -\frac{1}{2} \frac{d\beta}{ds} = 0$$

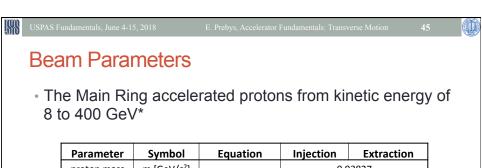
This is a mess, but we'll often restrict ourselves to the extrema of
$$\beta$$
, where
$$\alpha = -\frac{1}{2}\frac{d\beta}{ds} = 0 \Rightarrow \begin{pmatrix} x_1 \\ x_1' \end{pmatrix} = \begin{pmatrix} \frac{\beta_1}{\beta_0}\cos\Delta\psi & \sqrt{\beta_0\beta_1}\sin\Delta\psi \\ -\frac{1}{\sqrt{\beta_0\beta_1}}\sin\Delta\psi & \sqrt{\frac{\beta_0}{\beta_1}}\cos\Delta\psi \end{pmatrix} \begin{pmatrix} x_0 \\ x_0' \end{pmatrix}$$





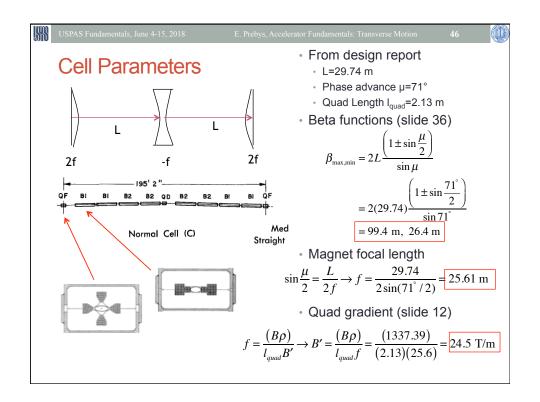


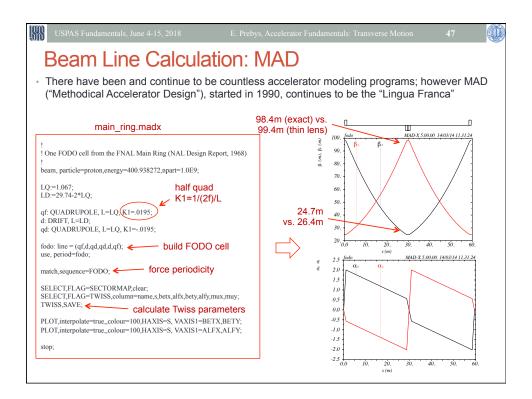


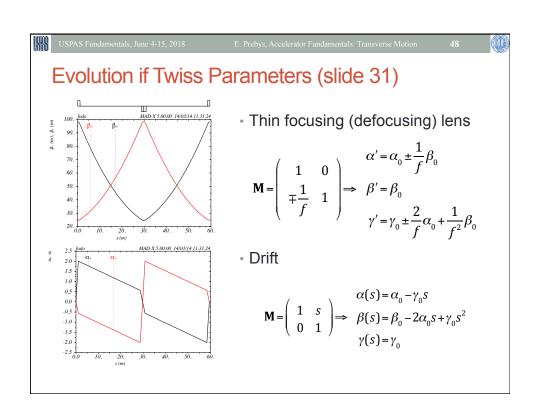


Parameter	Symbol	Equation	Injection	Extraction
proton mass	m [GeV/c²]		0.93827	
kinetic energy	K [GeV]		8	400
total energy	E [GeV]	$K + mc^2$	8.93827	400.93827
momentum	p [GeV/c]	$\sqrt{E^2-\left(mc^2\right)^2}$	8.88888	400.93717
rel. beta	β	(pc)/E	0.994475	0.999997
rel. gamma	γ	$E/(mc^2)$	9.5263	427.3156
beta-gamma	βγ	$(pc)/(mc^2)$	9.4736	427.3144
rigidity	(Βρ) [T-m]	p[GeV]/(.2997)	29.65	1337.39

*remember this for problem set









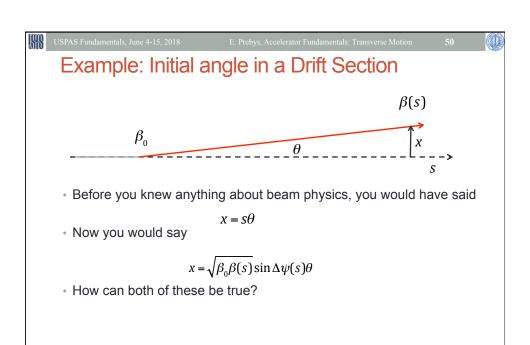
We have derived the generic transfer matrix to be

$$\begin{pmatrix} x_1 \\ x_1' \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{\beta_1}{\beta_0}} \left(\cos \Delta \psi + \alpha_0 \sin \Delta \psi\right) & \sqrt{\beta_0 \beta_1} \sin \Delta \psi \\ \frac{1}{\sqrt{\beta_0 \beta_1}} \left(\left(\alpha_0 - \alpha_1\right) \cos \Delta \psi - \left(1 + \alpha_0 \alpha_1\right) \sin \Delta \psi\right) & \sqrt{\frac{\beta_0}{\beta_1}} \left(\cos \Delta \psi - \alpha_1 \sin \Delta \psi\right) \end{pmatrix} \begin{pmatrix} x_0 \\ x_0' \end{pmatrix}$$

• Which means a particle on the axis $(x_0=0)$ with an angle $x'=\theta$ will follow a path given by

$$x = \sqrt{\beta_0 \beta(s)} \sin \Delta \psi(s) \theta$$

 But a particle doesn't "know" about lattice functions, so does this make sense



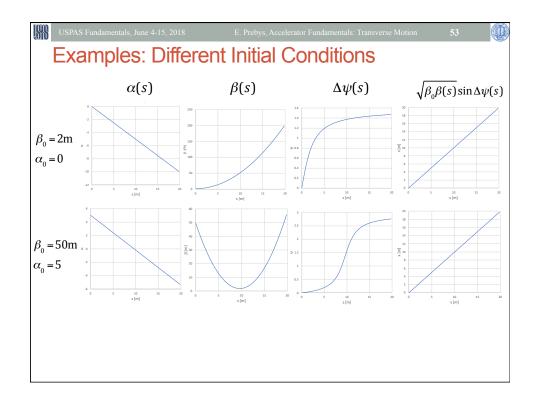
Evolution of Phase Angle
$$\Delta \psi = \int_{0}^{s} \frac{ds}{\beta(s)} = \int_{0}^{s} \frac{ds}{\gamma_{0}s^{2} - 2\alpha_{0}s + \beta_{0}} = \frac{1}{\gamma_{0}} \int_{0}^{s} \frac{ds}{s^{2} - 2\frac{\alpha_{0}}{\gamma_{0}}s + \frac{\beta_{0}}{\gamma_{0}}}$$

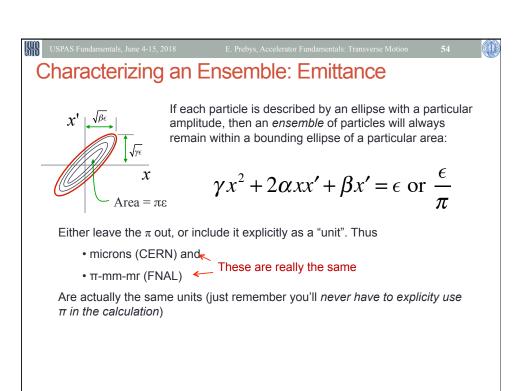
$$= \frac{1}{\gamma_{0}} \int_{0}^{s} \frac{ds}{\left(s - \frac{\alpha_{0}}{\gamma_{0}}\right)^{2} - \frac{\alpha_{0}^{2}}{\gamma^{2}} + \frac{\beta_{0}}{\gamma_{0}}} = \frac{1}{\gamma_{0}} \int_{0}^{s} \frac{ds}{\left(s - \frac{\alpha_{0}}{\gamma_{0}}\right)^{2} + \frac{-\alpha_{0}^{2} + \gamma_{0}\beta_{0}}{\gamma_{0}^{2}}} = \frac{1}{\gamma_{0}} \int_{0}^{s} \frac{ds}{\left(s - \frac{\alpha_{0}}{\gamma_{0}}\right)^{2} + \frac{1}{\gamma_{0}}} = \frac{1}{\gamma_{0}} \int_{0}^{s} \frac{ds}{\left(s - \frac{\alpha_{0}}{\gamma_{0}}\right)^{2} + \frac{1}{\gamma_{0}}\beta_{0}}} = \frac{1}{\gamma_{0}} \int_{0}^{s} \frac{ds}{\left(s - \frac{\alpha_{0}}{\gamma_{0}}\right)^{2} + \frac{1}{\gamma_{0}}\beta_{0}}} = \tan^{-1}(\gamma_{0}s - \alpha_{0}) - \tan^{-1}(-\alpha_{0})$$

$$= \tan^{-1}(-\alpha_{0}(s)) - \tan^{-1}(-\alpha_{0})$$

$$= \psi(s) - \psi_{0}$$

$$\alpha(s) \to -\infty \Rightarrow \psi(s) \to \frac{\pi}{4}$$







Definitions of Emittance

- · Because distributions normally have long tails, we have to adopt a convention for defining the emittance. The two most common are

• Gaussian (electron machines, CERN):
$$\epsilon = \frac{\sigma_x}{\beta_x}$$
; contains 39% of the beam

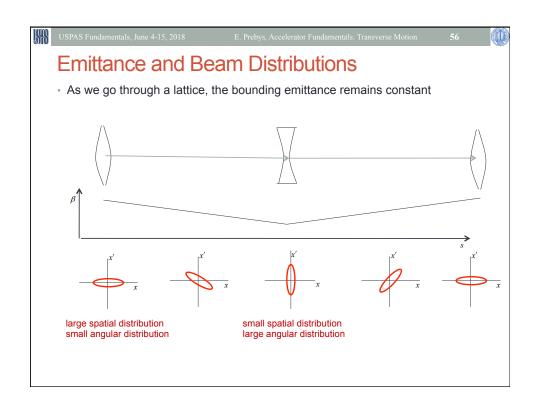
$$\rightarrow \sigma_x = \sqrt{\beta_x \epsilon}$$

• 95% Emittance (FNAL):

$$\epsilon_{95} = \frac{6\sigma_x^2}{\beta_x}$$
; contains 95% of the beam

$$\rightarrow \sigma_{x} = \sqrt{\frac{\beta_{x}\epsilon_{95}}{6}}$$

 In general, emittance can be different in the two planes, but we won't worry about that for now.





Distributions, Emittance, and Twiss Parameters

· The relationship between the lattice functions, RMS emittance and moment distributions is

$$\sigma_{x} = \sqrt{\frac{1}{N} \sum x^{2}} = \sqrt{\beta \epsilon}$$

$$\sigma_{x'} = \sqrt{\frac{1}{N} \sum_{x'}^{2}} = \sqrt{\gamma \epsilon}$$

$$\sigma_{xx'} = \frac{1}{N} \sum xx' = -\alpha \epsilon$$

· We can turn this around to calculate the emittance and lattice functions based on measured distributions

$$\epsilon = \sqrt{\sigma_x^2 \sigma_{x'}^2 - \sigma_{xx'}^2}$$

$$\beta = \frac{\sigma_x^2}{\epsilon}$$

$$\sigma_x^2 \sigma_{x'}^2 - \sigma_{xx'}^2 = (\beta \gamma - \alpha^2) \epsilon^2 = \epsilon^2$$

$$\gamma = \frac{\sigma_{x'}^2}{\epsilon}$$

$$\alpha = -\frac{\sigma_{xx'}}{\epsilon}$$

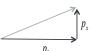


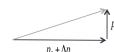




Adiabatic Damping*

 In our discussions up to now, we assume that all fields scale with momentum, so our lattice remains the same, but what happens to the ensemble of particles? Consider what happens to the slope of a particle as the forward momentum incrementally increases.





• If we evaluate the emittance at a point where α =0, we have

 $\epsilon = (\gamma_T x^2 + \beta_T x'^2)$ $d\epsilon = 2\beta_T x' dx' = -2\beta_T x'^2 \frac{dp}{p} = -2\epsilon \frac{dp}{p} \sin^2(\psi + \delta)$ $= \sqrt{\epsilon \gamma_T} \sin(\psi + \delta) \quad \langle d\epsilon \rangle = -2\epsilon \frac{dp}{p} \langle \sin^2(\psi + \delta) \rangle = -\epsilon \frac{dp}{p} \Rightarrow pd\epsilon + \epsilon dp = 0 \Rightarrow \epsilon p = \text{constant} = \epsilon_0 p_0$ $= \sqrt{\frac{\epsilon}{\beta_T}} \sin(\psi + \delta)$ $\epsilon = \epsilon_0 \frac{p_0}{p} = \frac{(\epsilon_0 \gamma_0 \beta_0)}{\gamma \beta} = \sqrt{\frac{\epsilon}{\beta_T}}$ "Normalized emittance" = constant!

*only true for protons!



Consequences of Adiabatic Damping

- · As a beam is accelerated, the normalized emittance remains constant
 - · Actual emittance goes down down

$$\epsilon = \frac{\epsilon_N}{\beta \gamma} \propto \frac{1}{p}$$

· Which means the actual beam size goes down as well

betatron function

RMS emittance

$$\sigma_x = \sqrt{\beta_x \epsilon} = \sqrt{\frac{\beta_x \epsilon_N}{\beta \gamma}} \text{ or } \sqrt{\frac{\beta_x \epsilon_{95}}{6 \beta \gamma}} \propto \frac{1}{\sqrt{p}}$$

The angular distribution at an extremum (α=0) is

$$\sigma_{x'} = \sqrt{\frac{\gamma_x \epsilon_N}{\beta \gamma}} = \sqrt{\frac{\epsilon_N}{\beta_x \beta \gamma}}$$

We almost always use normalized emittance for protons

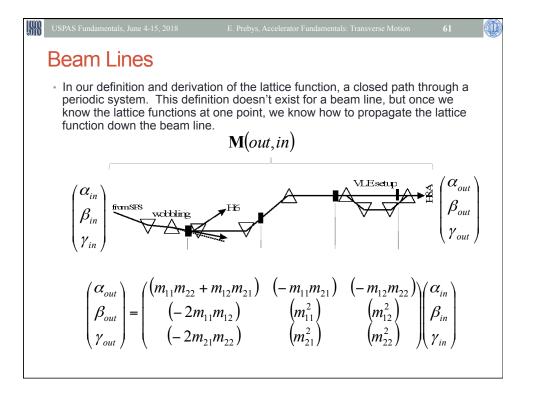


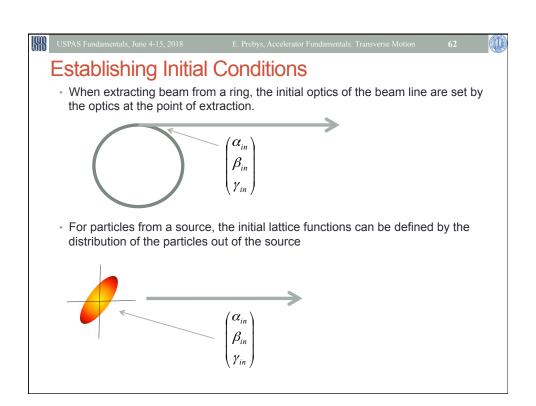
Example: FNAL Main Ring Revisited

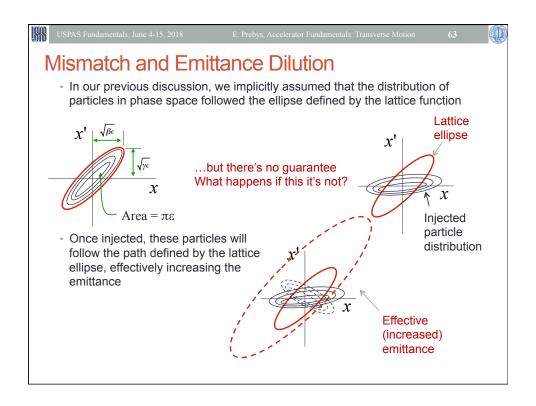
We normally use 95% emittance at Fermilab, and 95% normalized emittance of the beam going into the Main Ring was about 12 π-mm-mr, so the normalized RMS emittance would be

 $\epsilon_{RMS} \approx \frac{\epsilon_{95}}{6} = 2 \ \pi\text{-mm-mrad} = 2 \times 10^{-6} \ \text{m} \ \longleftarrow \ \text{We have divided out the "π"}$ We combine this with the equations (slide 45), beam parameters (slide 47) and lattice functions (slide 48) to calculate the beam sizes at injection and extraction.

		I		
Parameter	Symbol	Equation	Injection	Extraction
kinetic energy	K [GeV]		8	400
beta-gamma	βγ		9.4736	427.3144
normalized emittance	ϵ_N [m]		2x10 ⁻⁶	
beta at QF	β_{max} [m]		99.4	
beta at QD	β_{\min} [m]		26.4	
x size at QF	σ_x [mm]	$\sqrt{rac{eta_{ ext{max}}\epsilon_{ ext{N}}}{eta\gamma}}$	4.58	.68
y size at QF	σ_{y} [mm]	$\sqrt{rac{eta_{\min}\epsilon_{_N}}{eta\gamma}}$	2.36	.35
x ang. spread at QF	$\sigma_{\scriptscriptstyle x'}$	$\sqrt{\frac{\epsilon_N}{\beta_{\max}\beta\gamma}}$	46.1x10 ⁻⁶	6.9x10 ⁻⁶
y ang. spread at QF	$\sigma_{y'}$	$\sqrt{\frac{\epsilon_{_{N}}}{\beta_{\min}\beta\gamma}}$	89.5x10 ⁻⁶	13.3x10 ⁻⁶









- In spite of the name, g4beamline is not really a beam line tool.
 - Does not automatically handle recirculating or periodic systems
 - Does not automatically determine reference trajectory
 - Does not match or directly calculate Twiss parameters
 - Fits particle distributions to determine Twiss parameters and statistics.
- Nevertheless, it's so easy to use, that we can work around these shortcomings
 - · Create a series of FODO cells
 - Carefully match our initial particle distributions to the calculations we just made.

